Data processing of M-100 meteorological rocket system

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1. Introduction

The M-100 vehicle is a two-stage solid propellant rocket which can reach a maximum altitude of 90 km, when fired at 83° elevation carrying a meteorological payload of weight 66 kg. The standard M-100 rocket payload consists of the following:

(a) Four tungsten rhenium (40 micron) wire thermometers for measuring temperature in different ranges covering -100°C to +350°C.
(b) Two Pirani (hot wire) manometers for measuring pressure from 50 to 5×10⁻³ mm of mercury.
(c) Other supplementary thermometers for monitoring payload housing temperature and manometer temperature.
(d) Electronic devices including a mechanical 60 channel commutator, telemetry transmitter 22 MHz, 1780 MHz, radar transponder, antenna system and power supply.

The unbalanced Wheatstone's bridge circuit is used for telemetering the manometer and thermometer data to the ground. Two telemetry receivers with panoramic and photographic attachments record them along with the timing pulses (10 pps) from lift-off. The steeple portion of the payload containing the sensors opens at 60 seconds and the whole payload is separated at 70 seconds from the rocket and attains maximum altitude of 90 km at 140 seconds. A 35 square metre area hemispherical nylon non-reflecting parachute exerts a stabilizing influence on the payload and fully opens during descent at an altitude of 60-65 km around 200 sec.

The Meteor radar (1780 MHz) tracks the payload in the transponder mode and the tracking data — azimuth, elevation and slant range — are photographed every second for the first 10 minutes. Processing the telemetry and radar films, initial data are obtained. The preliminary data are fed to either Minsk-22 or IBM-360/44 computer for getting the final results. Computer programmes have been worked out for obtaining the ROCOB data in the format as per the latest WMO recommendation introduced from 1 January 1972, in the punched tape form ready for transmission to all national as well as international meteorological centres. The preliminary and final data reduction techniques used in the M-100 rocket system are briefly described.

2. Processing of telemetry data

All the telemetry signals in one cycle of 5 seconds characterise the readings of the atmospheric parameters recorded on the photographic film (Fig. 1). Each signal is registered on the film as three dot points that are plotted close to one another. These points are usually well distinguished from other interference signals. The vertical displacement of a signal from the zero line on the photographic film varies proportionately to the voltage supplied from the bridge output to the transmitter and depends upon the value of the parameter being measured. The initial processing of the telemetered data includes a deciphering of the signals available on the film in certain time intervals and their conversion into values of temperature and pressure with the help of graduated graphs. The deciphering consists of finding out the signals of a given transmitter on the film with the aid of a code table and taking their readings (voltages) against time (Fig. 2). Ten pps records are
Fig. 1. Typical telemetry signals recorded on photographic film in one cycle 5 seconds 60 channels
(Flight No. 08-50.)

Fig. 2. Deciphered telemetry data (Flight No. 08-50)
also available on the side of the film for taking the time accurately.

The telemetry signals are deciphered by means of a decoder which projects the enlarged signals from the telemetry film to a special screen. The voltages obtained during the operation of transmitters can be taken from the film making use of numbered scales which can be moved on the screen.

Deciphering is carried out for all cycles beginning from 70 seconds to 300 seconds every cycle, every alternate cycle from 300 seconds to 600 seconds, every third cycle from 600 seconds to 1000 seconds, and thereafter every tenth cycle. The voltage readings taken from the film are converted into values of temperature and pressure with the help of graduated curves after calibration and plotted on graph paper with the aid of typewriter against time with the following scales:

1 cm = 2 sec from 50 to 300 sec.
1 cm = 10 sec from 300 to 1000 sec.
1 cm = 200 sec from 1000 sec till end.

Average curve is fitted to the data plotted for the four thermometers (Fig. 3). Manometer data processing is done separately (Fig. 4). Filament temperature, steelle temperature, log $P$ and manometer temperature values are picked up from the above plots.

3. Meteor radar data processing

A typical film record of the Meteor radar tracking data — azimuth, elevation and slant range — is shown in Fig. 5. The readings are tabulated every 5 sec interval starting from 70 to 600 sec and every 30 sec intervals from 450 sec till elevation falls below 10 mils ($^\circ$). The readings are taken after 10 min from the Meteor data print out record. These readings are plotted for assessing the tracking data (Fig. 6). Wherever radar tracking data are not good, smoothed readings are taken from the graph accurate to 0.01 km for slant range, one mil for elevation and azimuth. The tracking values of the angles and slant range at 5 sec interval are used for computing the rocket trajectory co-ordinates, speed as well as wind velocity.

4. Final data reduction

Manually processed preliminary data — radar tracking data, temperature and manometer data at 5 seconds interval — are tabulated (Fig. 7); punched on tape and fed into Minsk-22 computer along with the standard M-100 computer programme for the final data reduction. The computer programme permits to solve the following problems —

1. Preparation of original data for processing.

2. Processing of radar data:

   (a) calculation of the co-ordinates of rocket and trajectory,
   (b) calculation of the components and total velocity of rockets, and
   (c) calculation of the wind components, speed and direction.

3. Co-relation of original data to standard altitude and restoration of the results of tracking.
DATA PROCESSING OF MET ROCKET SYSTEM

Fig. 4. Manometer data processing (Flight No. 08-50)

Fig. 5. Typical film record of Meteor reader tracking data

Fig. 6. Meteor data smoothing—azimuth, elevation and slant-angle
(4) Processing of telemetry data:

(a) calculation of temperature, pressure and density at standard altitudes using the results of thermometer measurements, and

(b) calculation of atmospheric pressure at standard altitudes as per the results of manometer measurements.

(5) Storage and formulation of the results.

5. Method of verification and checking

The computer print out results are plotted for further analysis and checking in respect of velocity altitude, temperature, density and wind. Typical M-100 flight data analysis are shown in Figs. 8-10 (velocity, height, time curve, temperature and wind profiles). Nearest available high level radiosonde RAOB and CIRA 1965 data are also plotted along with the ROCOB for comparison. In case of telemetry data failure, only wind data is reported. In the absence of accurate radar tracking data, but telemetry data available, temperature computation is less reliable. However, approximate temperature calculation can be carried out upto 50 km altitude based on the nearest available flight having the same apogee and other trajectory characteristics. If the steeple thermometer does not function properly in any flight the previous flight data can be utilised for computation. Normally the steeple temperature may not vary from flight to flight in a particular season.

6. Chaff wind data processing

Additional fibre glass and copper chaff payloads
have been flown successfully in M-100 rockets from Thumba since November 1972 to collect wind data in the upper mesospheric region 60-90 km which is not normally covered by the standard M-100 rocket system. The copper chaff data provide interesting overlapping wind observation below 60 km with parachute. In the Soviet's system 3 or 4 fibre glass chaff bundles are ejected at 10 km intervals from 90 km downwards and the different chaff clouds are tracked by a single radar system. As this special radar facility is not available at Thumba, two type chaffs — copper and fibre glass — are ejected at 70 sec and 145 sec corresponding to altitudes 70 and 90 km respectively. The total LV-300 radar is utilised to track the two chaff clouds alternately at 10-minute interval. The chaff cloud tracking data recorded on three strip charts in the total radar system are analysed manually and the readings converted into azimuth, elevation and slant range at 5 sec interval for the first 10 min and thereafter every 30 sec by a simple computer programme. Final chaff wind data reduction is carried out by a standard computer programme in IBM-360/44 computer giving due allowance for the radar hunting and smoothing. The computed height is smoothed by fitting a second degree curve taking 13 points each. Average winds over one km thickness are computed and printed out along with wind components and fall velocity. Extrapolated values are rejected while reporting.

7. Concluding remarks

The Pirani gauge manometer data processing at Thumba was not found to be satisfactory mainly due to pre-flight calibration inaccuracy. In a large number of flights, pressure sensors did not
operate well. Pressure and density data were computed, extrapolating radiosonde pressure data at the levels of 10, 15, 20, 25 and 30 km. The pressure values thus computed were found to be in good consistency. Meteor radar tracking data are very important in the data reduction of temperature from telemetry records. The accuracy of temperature measurement is ±3°C below 50 km, ±5°C from 50 to 60 km and ±7 to 10°C above 60 km. The error in the wind measurement is of the order of 5 m/s in the region 40-50 km and 10 m/s above 50 km.

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